

10.) Sources of magnetic fields

10.1) \vec{B} fields due to moving point charges10.2) \vec{B} fields due to currents

10.3) Ampere's Law

10.1) Magnetic fields caused by moving charges* Key Point: All magnetic fields result from charges in motion.* Fundamental Law

$$\vec{B} = \frac{\mu_0}{4\pi} \frac{q \vec{v} \times \hat{r}}{r^2}$$

unit vector
($\hat{r} = \frac{1}{r} \vec{r}$)

This is actually a bit tricky to interpret, so let's break it down:

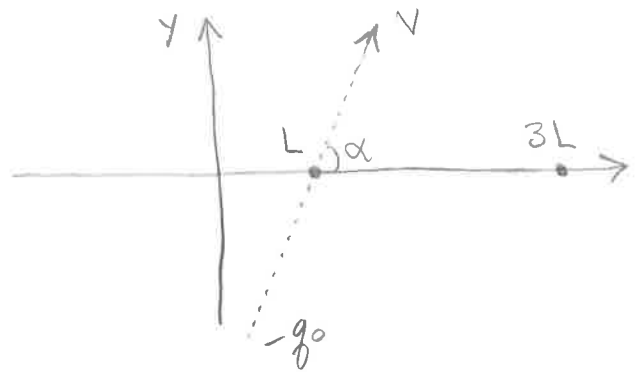
(a) The constant μ_0 is called the "permeability of free space", analogous to ϵ_0 for electric fields

(b) q is just the charge of the particle in motion
(sign matters!)

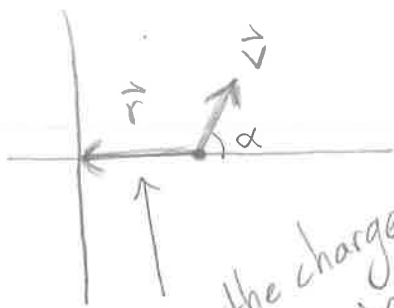
(c) \vec{v} is the instantaneous velocity vector

(d) \vec{r} is the vector from the location of the charge to the location where we want to measure \vec{B} .

Example: Consider the dotted trajectory of a charge $-q_0$ with speed v as shown. At the instant the charge crosses the x-axis, what is the instantaneous magnetic field at the origin? At the point $3L\hat{i}_x + 0\hat{i}_y$?



Solution: At the instant $-q_0$ crosses the x-axis, we can draw the \vec{v} and \vec{r} vectors as follows



from the charge
and to the point
where we compute \vec{B} .

Note that \vec{r} points toward the origin.

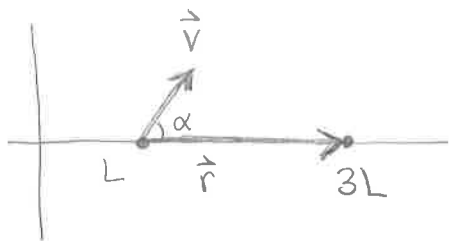
$$\begin{aligned}\vec{v} \times \hat{r} &= |\vec{v}| |\hat{r}| \sin \theta \odot \\ &= (v)(1) \sin(\pi - \alpha) \odot \\ &= v \sin \alpha \odot\end{aligned}$$

↑ out of page

$$\Rightarrow \vec{B} = \frac{\mu_0}{4\pi} (-g_0) \frac{v \sin \alpha}{L^2} \text{ out of page} = \boxed{\frac{\mu_0}{4\pi} g_0 \frac{v \sin \alpha}{L^2} \text{ into page}}$$

This is only the \vec{B} field at the origin.

At the location $3L \hat{i}_x + 0 \hat{i}_y$ we find



$$\vec{v} \times \hat{r} = |\vec{v}| |\hat{r}| \sin \theta \otimes$$

$$= v (1) \sin \alpha \otimes$$

$$= v \sin \alpha \otimes \leftarrow \text{into page}$$

$$\Rightarrow \vec{B} = \frac{\mu_0}{4\pi} (-g_0) \frac{v \sin \alpha}{(2L)^2} \otimes$$

$$\boxed{\vec{B} = \frac{\mu_0}{4\pi} \frac{g_0 v \sin \alpha}{4L^2} \otimes}$$

10.2) Magnetic fields due to currents

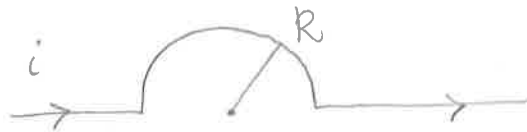
⊛ In 1820 Hans Oersted discovered that a current-carrying wire caused a compass needle to move.

⊛ From the point charge rule above, we can derive the total \vec{B} field due to the many moving charges in a current:

$$\begin{aligned}
 d\vec{B} &= \frac{\mu_0}{4\pi} dq \frac{\vec{v} \times \hat{r}}{r^2} \\
 &= \frac{\mu_0}{4\pi} (\rho_c dV) \frac{\vec{v} \times \hat{r}}{r^2} \quad (\vec{V} = \text{volume}, \vec{v} = \text{velocity}) \\
 &= \frac{\mu_0}{4\pi} (\rho_c A dl) \frac{\vec{v} \times \hat{r}}{r^2} \\
 &= \frac{\mu_0}{4\pi} (\rho_c A v) \frac{d\vec{l} \times \hat{r}}{r^2} \quad (\vec{v} \text{ and } d\vec{l} \text{ are parallel})
 \end{aligned}$$

$$\boxed{d\vec{B} = \frac{\mu_0}{4\pi} i \frac{d\vec{l} \times \hat{r}}{r^2}} \quad \text{Biot-Savart Law}$$

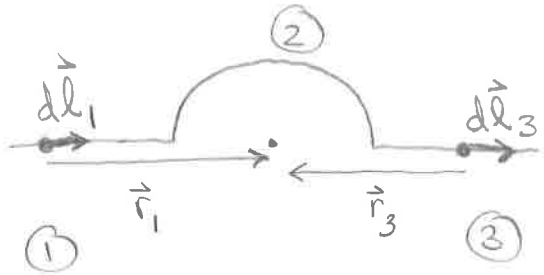
Example: Consider the current-carrying wire shown below, where the current i flows to the right and the circle radius is R . What is the \vec{B} field at the center of the circle?



Solution:

In principle we need to add up all contributions to the \vec{B} field at the center due to the 3 separate sections of wire.

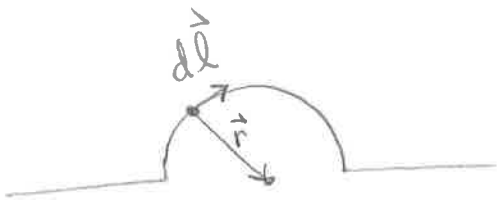
The straight sections turn out to be trivial because $d\vec{l}$ is parallel to \vec{r}



$$d\vec{l}_1 \times \vec{r} = 0$$

$$d\vec{l}_3 \times \vec{r} = 0$$

Only the semicircle part contributes to the \vec{B} field at the center:



Note that tangent vector to circle is perpendicular to radius vector

$$d\vec{l}_2 \times \hat{r} = |d\vec{l}_2| |\hat{r}| \sin\theta$$

$$= dl_2 (1)(1)$$

$$= dl_2$$

$$\Rightarrow \vec{B} = \int \frac{\mu_0}{4\pi} i \frac{d\vec{l} \times \hat{r}}{r^2} \quad r = R (\text{constant})$$

$$= \frac{\mu_0 i}{4\pi R^2} \underbrace{\int dl}_{\text{length of semicircle is } \pi R}$$

$$= \frac{\mu_0 i}{4\pi R^2} (\pi R) = \frac{\mu_0 i}{R}$$

⊗ For more complicated problems, use these 5 steps:

① Break up current into small pieces $i d\vec{l} = i \{d\vec{x}, d\vec{y}, R d\theta \hat{i}_\theta\}$

② Determine integration region $\int dl$

③ Compute $|d\vec{B}|$ from small current segment $d\vec{l}$ at an arbitrary point l within integration region:

$$|d\vec{B}| = \frac{\mu_0 i}{4\pi} \frac{|d\vec{l} \times \hat{r}|}{r^2} = \frac{\mu_0 i}{4\pi} \frac{|d\vec{l}| \sin \theta_{lr}}{r^2}$$

where θ_{lr} is the angle between $d\vec{l}$ and \hat{r} .

④ Write θ_{lr} and/or r in terms of integration variable.

⑤ Integrate and determine direction of \vec{B} from right-hand-rule for $d\vec{l} \times \hat{r}$.

⑤* To integrate over θ for circular sections of wire, change $dl = R d\theta$ and always choose increasing θ direction to be along current direction

Exam 2, 2015,

1. (25 points) A very thin wire lies in the x, y plane. It has the shape shown below consisting of two circular segments, centered at the origin, connected by segments along radii. There is a current i in the wire as shown. Find the magnetic field at the origin.

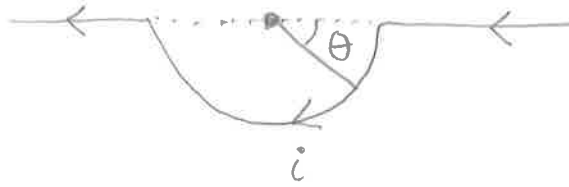


Law

Application

Result

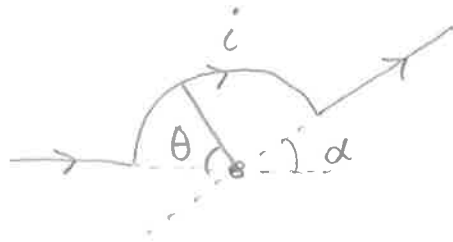
For instance,



$$\int_0^\pi d\theta$$



$$\int_0^\pi d\theta$$



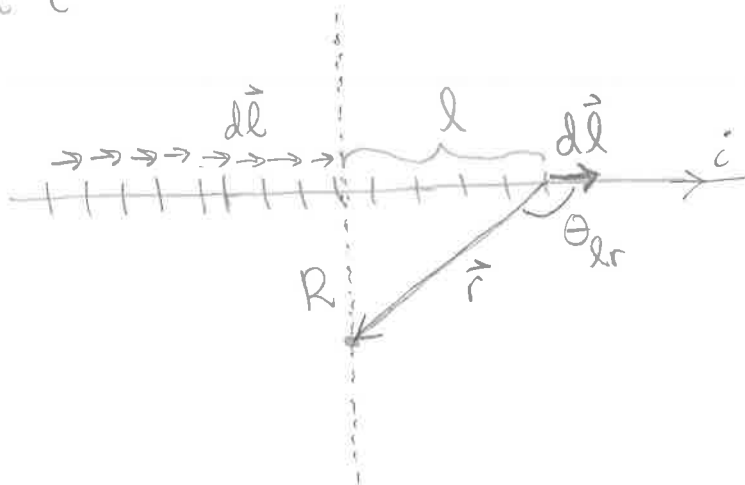
$$\int_0^{\pi - \alpha} d\theta$$

Example:

Magnetic field a distance R from an infinitely long wire carrying current i

Solution:

①



② $\int_{-\infty}^{\infty} dl$

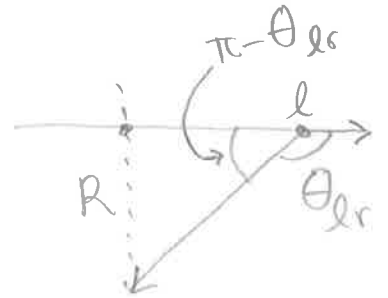
③ $|\vec{dB}|$ due to small current segment $i d\vec{l}$ at the arbitrary point l :

$$dB = \frac{\mu_0 i}{4\pi} \frac{d\vec{l} \times \vec{r}}{r^2}$$

$$= \frac{\mu_0 i}{4\pi} \frac{dl \sin\theta_{lr}}{\sqrt{R^2 + l^2}}$$

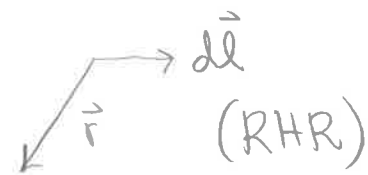
$$= \frac{\mu_0 i}{4\pi} \frac{dl \sin(\pi - \theta_{lr})}{\sqrt{R^2 + l^2}}$$

$$= \frac{\mu_0 i}{4\pi} \frac{dl}{\sqrt{R^2 + l^2}} \frac{R}{\sqrt{R^2 + l^2}}$$



$$⑤ \quad B = \frac{\mu_0 i R}{4\pi} \int_{-\infty}^{\infty} \frac{dl}{(R^2 + l^2)^{3/2}} = \frac{\mu_0 i R}{4\pi} \left[\frac{2}{R^2} \right]$$

$$\vec{B} = \frac{\mu_0 i}{2\pi R} \text{ (into page)}$$

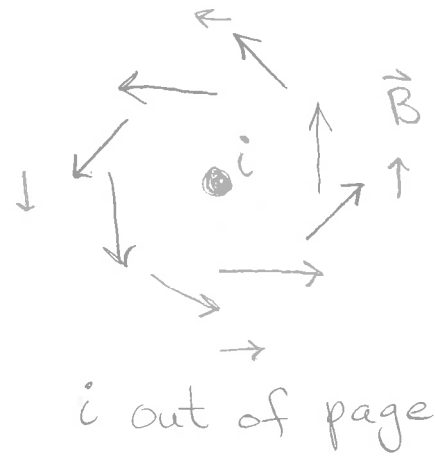
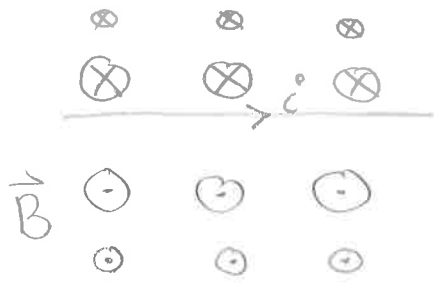


10.3) Ampere's Law

The above result for an infinitely long current carrying wire was fairly involved.

There is a much easier way to obtain same result.

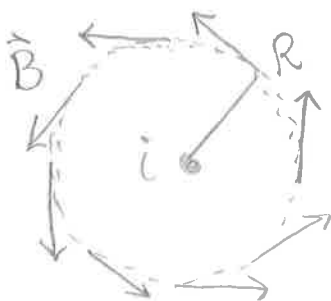
* Key Point: Magnetic fields "circulate" around current-carrying wires



* RHR: Point thumb in direction of current, then fingers curl in direction of \vec{B} field circulation.

* The curling of a vector field can be measured with a closed line integral: $\oint \vec{B} \cdot d\vec{\ell}$.

Example: For the case above with the current flowing out of page, how does $\oint \vec{B} \cdot d\vec{\ell}$ vary with the choice of the radius R of the circulating path?



$$B = \frac{\mu_0 i}{2\pi R} \quad (\text{proved previously from Biot-Savart})$$

$$\oint \vec{B} \cdot d\vec{\ell} = \int_0^{2\pi R} B dl = \int_0^{2\pi R} \frac{\mu_0 i}{2\pi R} dl = \frac{\mu_0 i}{2\pi R} (2\pi R)$$

\vec{B} parallel to $d\vec{\ell}$

$$= \underline{\underline{\mu_0 i}}$$

⊛ This result is independent of R (any radius circle would produce same result).

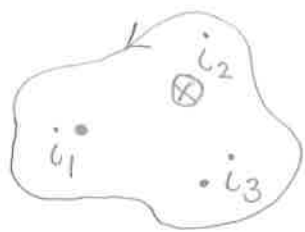
⊛ Even if we had chosen a non-circular path, the result would have been identical



$$\boxed{\oint \vec{B} \cdot d\vec{\ell} = \mu_0 i_{enc}} \quad \text{Ampere's Law}$$

⊛ Note: Loop must be counterclockwise to get correct sign.

Example: What is the line integral of $\vec{B} \cdot d\vec{\ell}$ for the loop below?



At all points along this path we could compute \vec{B} separately from the 3 currents and then integrate.

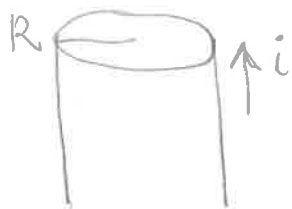
But that is too complicated!

$$\text{Instead, } \oint \vec{B} \cdot d\vec{\ell} = \mu_0(i_1 + i_3 - i_2)$$

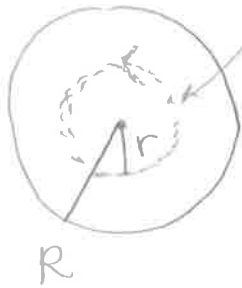
⊗ Therefore, from Ampere's Law we can easily calculate a very complicated quantity $\oint \vec{B} \cdot d\vec{\ell}$, but who cares?

⊗ Just like with Gauss's Law, if symmetry let's us take B outside of integral, then we can compute a more useful quantity: the magnetic field.

Example: Consider a very thick current carrying wire of cross sectional radius R and uniform current i . What is the magnetic field inside and outside the wire?



From Ampere's Law, we need to calculate the current enclosed by an Amperian loop



Amperian loop of radius r encloses some of i but not all.

How much?

Recall current density definition:

$$J = \frac{\dot{i}}{A}$$

$$J = \frac{\dot{i}}{\pi R^2}$$

$$\begin{aligned} \Rightarrow i_{enc} &= J A_{enc} \\ &= J (\pi r^2) \\ &= \frac{\dot{i}}{\pi R^2} (\pi r^2) \end{aligned}$$

$$i_{enc} = i \frac{r^2}{R^2}$$

As $r \rightarrow R$, we see that $i_{enc} \rightarrow i$ (the full current)

$$\Rightarrow \text{Ampere's Law: } \oint \vec{B} \cdot d\vec{l} = \mu_0 i \frac{r^2}{R^2}$$

From symmetry B must be constant along path.

$$B \oint dl = \mu_0 i \frac{r^2}{R^2}$$

$$B(2\pi r) = \mu_0 i \frac{r^2}{R^2}$$

$$\Rightarrow B = \frac{\mu_0 i}{2\pi R^2} r \quad (\text{for } r < R)$$

For $r > R$ the only change is that now $i_{\text{enc}} = i$

$$\Rightarrow \oint \vec{B} \cdot d\vec{\ell} = \mu_0 i_{\text{enc}}$$

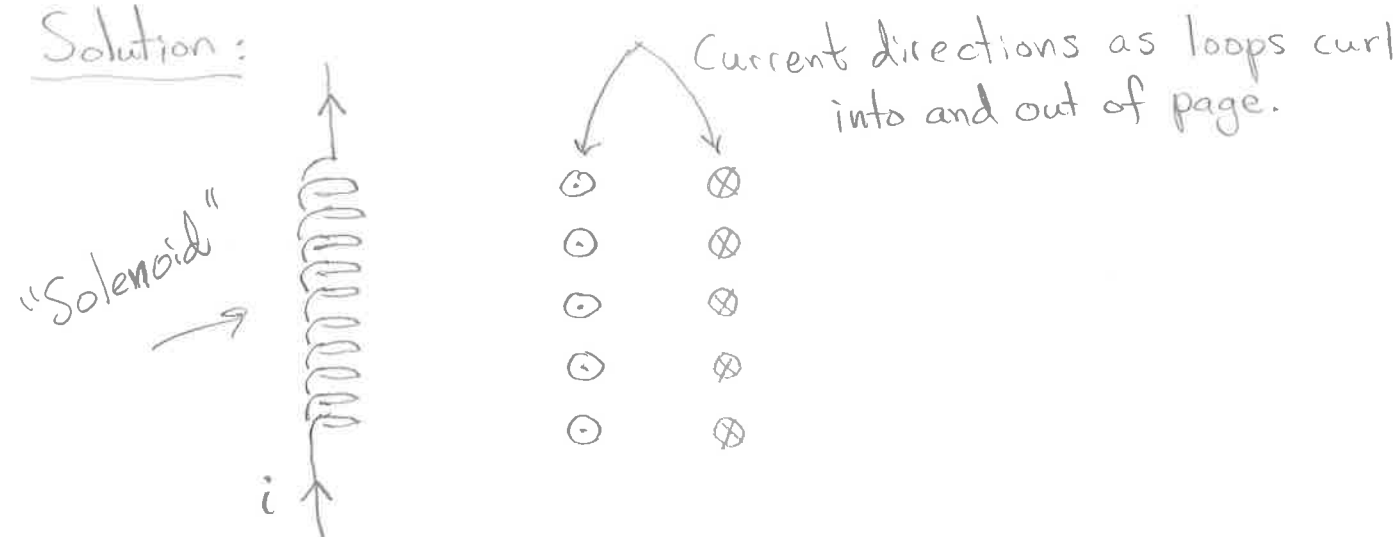
$$B(2\pi r) = \mu_0 i$$

$$B = \frac{\mu_0 i}{2\pi r} \quad \text{for } r > R$$

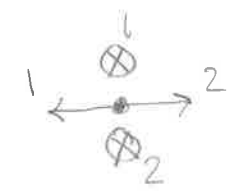
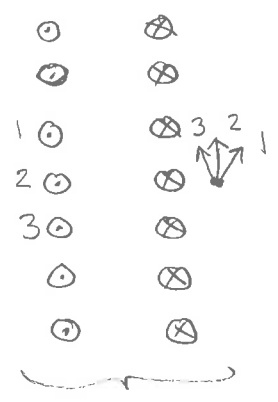
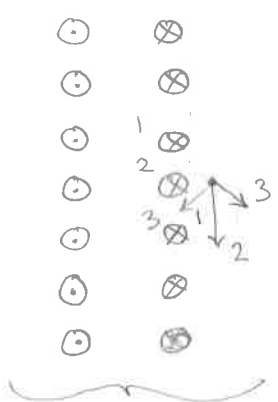
this is same as for a long thin wire!

Example: What is the magnetic field inside and outside a tightly wound coil loop with N turns and length L ?

Solution:



First, \vec{B} field outside is very small (difficult to prove rigorously)



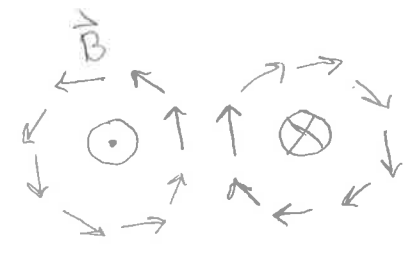
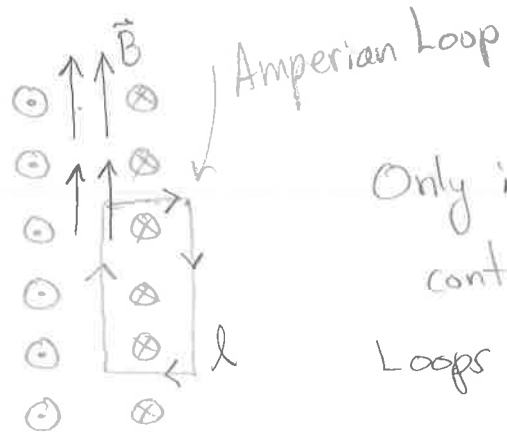
B field between also nearly 0.

Fewer currents on right-hand side contribute, but they're larger in magnitude

More currents on left-hand side contribute, but they're smaller in magnitude

Overall the two sets of contributions nearly cancel

\vec{B} field inside:



\vec{B} fields add up in center.

Only inside part of loop picks up a contribution to $\oint \vec{B} \cdot d\vec{l} = Bl$.

Loops enclosed $n = \left(\frac{N}{L}\right)l$ ← length of Amperian Loop
 ↑ loop number density

$$\Rightarrow \oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$Bl = \mu_0 i \left(\frac{N}{L}\right)l \Rightarrow$$

$$B = \mu_0 i \frac{N}{L}$$